

Testing VisionFive GPIO

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Legal Statements

Important legal notice before reading our documentation.

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Preface

About this guide and technical support information.

About this document

This application note provides two methods to test VisionFive GPIO:

Revision History

Table 0-1 Revision History

Version	Released	Revision	
V1.0	2021-12-15	Preliminary release.	
V1.1	2021-12-27	In the Running Demo Codes section:	
		 Added description for the app directory. 	
		• Added description for the rsync command.	
		 Added description for <user_name>.</user_name> 	
		• Fixed a typo.	

Notes and notices

The following notes and notices might appear in this guide:

• 🚺 Tip:

Suggests how to apply the information in a topic or step.

Note:

Explains a special case or expands on an important point.



Important:

Points out critical information concerning a topic or step.



• **()** CAUTION:

Indicates that an action or step can cause loss of data, security problems, or performance issues.



Indicates that an action or step can result in physical harm or cause damage to hardware.

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1. Introduction

This application note provides two methods to test VisionFive GPIO:

- Test with command lines.
- Test with demo code.

2. Preparation

Before executing the demo program, make sure you prepare the following:

2.1. Preparing Hardware

Prepare the following hardware items before running the demo code:

Туре	м/0 [*]	Item	Notes
General	М	StarFive single board computer	The following boards are applicable:
			• StarLight
			• VisionFive
General M	М	• 16 GB (or more) micro-SD card	These items are used for flashing Fe-
		micro-SD card reader	dora OS into a micro-SD card.
		 Computer (Windows/MAC/Lin- ux) 	
		 USB to serial converter (3.3 V I/ O) 	
		• Ethernet cable	
		• Power adapter (5 V / 3 A)	
		• USB Type-C Cable	
GPIO	Μ	An oscilloscope	The oscilloscope is used to verify the GPIO voltage.

Table 2-1 Hardware Preparation



Note:

*: M: Mandatory, O: Optional

2.2. Preparing Software

- Software Environment:
 - PC: Ubuntu 20.04
 - RISC-V Platform: Linux 5.16.0
- Flash Fedora OS into a Micro-SD card and compile and replace dtb files as described in the *Preparing Software* section in *StarFive 40-Pin GPIO Header User Guide*.

3. Testing GPIO with Command Lines

Test the GPIO0 as described in the *Configuring GPIO* section in the *StarFive 40-Pin GPIO Header User Guide*.

4. Running Demo Codes

To run the demo code, perform the following:

4.1. Compiling the Source Code

To compile the source code, perform the following:

1. Save the following source code for C language as test-gpio.c to your desired directory under Ubuntu:

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <string.h>
#include <errno.h>
#include <fcntl.h>
#include <sys/stat.h>
#define GPIO44 492
#define GPIO22 470
#define GPIO_KEY1
               GPIO44
#define FISCV_GPIO GPI022
#define MAX_BUF 128
                                 //Define array size
#define StarF_Gpio_Dir "/sys/class/gpio" //GPIO control paths
* Function Name: StarF_gpio_export
* Description: Set the pin number
* return value: 0 Success; Others: fail
 Data version Author Application Name
   _____
* 2021/12/08 V1.0 zheng.xu test gpio
* /
int StarF_gpio_export(unsigned int gpio)
{
   int fd, len;
   char buf[MAX_BUF];
// /sys/class/gpio/export
   fd = open( "/sys/class/gpio/export", O_WRONLY);
   if (fd < 0) {
     perror("gpio/export");
     return fd;
   }
```

```
len = snprintf(buf, sizeof(buf), "%d", gpio);
   write(fd, buf, len);
   close(fd);
  return 0;
}
* Function Name: StarF_gpio_unexport
* Description: Cancel the GPIO pin number
* return value: 0 Success; Others: fail
* Data version Author Application Name
              V1.0 zheng.xu test gpio
* 2021/12/08
* /
int StarF_gpio_unexport(unsigned int gpio)
{
   int fd, len;
   char buf[MAX_BUF];
// /sys/class/gpio/unexport
   fd = open("/sys/class/gpio/unexport", O_WRONLY);
   if (fd < 0) {
      perror("gpio/export");
      return fd;
   }
   len = snprintf(buf, sizeof(buf), "%d", gpio);
   write(fd, buf, len);
   close(fd);
   return 0;
}
/ * * * * * * * * * * * * * * * * * *
* Function Name: StarF_gpio_set_dir
* Description: Set GPIO pin I/O
* return value: 0 Success; Others: fail
  Data version Author Application Name
*
* 2021/12/08 V1.0 zheng.xu test gpio
* /
int StarF_gpio_set_dir(unsigned int gpio, unsigned int out_flag)
{
   int fd, len;
   char buf[MAX BUF];
```

```
// /sys/class/gpio/gpioN/direction
   len = snprintf(buf, sizeof(buf),
StarF_Gpio_Dir "/gpio%d/direction", gpio);
   fd = open(buf, O_WRONLY);
   if (fd < 0) {
      perror(buf);
      return fd;
   }
   if (out_flag)
                              //'1' set to output
      write(fd, "out", 4);
   else
                               //'0' set input
      write(fd, "in", 3);
   close(fd);
   return 0;
}
* Function Name: StarF_gpio_set_dir
* Description: Set GPIO high & low levels
* function parameters:@GPIO Set GPIO number for the output level
                   value 1: Set gpio output to high |evel: 0: Set
gpio output to low level.
* return value: 0 Success; Others: fail
  Data version Author Application Name
* 2021/12/08 V1.0 zheng.xu test gpio
*/
int StarF_gpio_set_value(unsigned int gpio, unsigned int value)
{
   int fd, len;
   char buf[MAX_BUF];
// /sys/class/gpio/gpioN/value
   len = snprintf(buf, sizeof(buf), StarF_Gpio_Dir "/gpio%d/value",
qpio);
   fd = open(buf, O_WRONLY);
   if (fd < 0) {
      perror(buf);
      return fd;
   }
   if (value)
                               //'1' output is high level
      write(fd, "1", 2);
                                //'0' output is Low level
   else
      write(fd, "0", 2);
```

```
close(fd);
   return 0;
}
* Function Name: StarF_gpio_get_value
* Description: Read GPIO high & low levels
* function parameters:@GPIO Set GPIO number for the output level
                  value 1: Set gpio output to high |evel; 0: Set
gpio output to low level.
* return value: 0 Success; Others: fail
 Data version Author Application Name
   _____
* 2021/12/08 V1.0 zheng.xu test gpio
* * * * * * * * * * * * * * * *
*/
int StarF_gpio_get_value(unsigned int gpio, unsigned int *value)
{
   int fd, len;
   char buf[MAX_BUF];
   char ch;
// /sys/class/gpio/gpioN/value
   len = snprintf(buf, sizeof(buf), StarF_Gpio_Dir "/gpio%d/value",
gpio);
   fd = open(buf, O_RDONLY);
   if (fd < 0) {
     perror("gpio/get-value");
     return fd;
   }
  read(fd, &ch, 1);
                             //Read the external input level
   if (ch != '0') {
                             //'1' Input is high level
      *value = 1;
   } else {
                             //'0' Input is Low level
      *value = 0;
   }
   close(fd);
  return 0;
}
* FunctionName: main
* Description:
* function parameters:
* return value: 0 Success; Others: fail
```

```
| 4 - Running Demo Codes
```

```
*
  Data version Author Application Name
*
             V1.0 zheng.xu
* 2021/12/08
                             test gpio
*/
int main(int argc, char **argv) {
  unsigned int i;
  unsigned int value1,value2;
  printf("\t******* StarF_GPIO_TEST_DEMO *********\n");
  printf("\t******* Version date: 2021/12 ********\n");
  printf("Gpio begin to init\r\n");
  StarF_gpio_export(FISCV_GPIO);
                                        //export gpio
Gpio
  StarF_gpio_set_dir(FISCV_GPIO, 1);
                                        //set as output
  printf("Gpio init ok\r\n");
  /* Confirm INIT_B Pin as High */
while(1)
{
 StarF_gpio_set_value(FISCV_GPIO, 1); //output high
 printf("Gpio off\r\n");
 usleep(500000);
                                 //delay
 StarF_gpio_set_value(FISCV_GPIO, 0);
                                 //output low
 printf("Gpio on\r\n");
 usleep(500000);
                                  //delay
  }
  StarF_gpio_unexport(FISCV_GPIO);
                                    //unexport gpio Gpio
  return 0;
}
```

2. (Optional) Install the tool to compile. The following is an example to install:

sudo apt-get install gcc-riscv64-linux-gnu

Information:

- This step can be skipped if the tool has been installed.
- After successful installation, check the version by running: linus@starfive\$ riscv64-linux-gnu-gcc -v. The following is the example output:

```
Figure 4-1 Example Output
```

Thread model: posix gcc version 9.3.0 (Ubuntu 9.3.0-17ubuntu1~20.04)

Result: The executable test-gpio file is generated in the current directory.

3. Compile the source code by executing the following:

```
riscv64-linux-gnu-gcc -o test-gpio test-gpio.c
```

4. Execute the following to see if the compilation is successful:

file test-gpio

Result: UCB RISC-V in the following output indicates the compilation is successful:

```
Riscv@starfive:~/work/app$ file test-gpio
test-gpio: ELF 64-bit LSB executable, UCB
RISC-V, version 1 (SYSV), dynamically linked,
interpreter /lib/ld-linux-riscv64-lp64d.so.1, for GNU/Linux 4.15.0,
BuildID[shal]=476d5a99c84f995d03227a18285222ac25e2cd0d, not stripped
c-v2x@starfive:~/work/app$
```

4.2. Testing GPIO with Demo Codes

- 1. Power on the VisionFive, and check the GPIO22 voltage changes.
- 2. Execute the following command in Ubuntu to upload the executable file test-gpio to your desired directory of the board, for example, test:

rsync ./test-gpio <User_Name>@<Board_IP_Address>:/home/riscv/test

Information:

- <User_Name>: Your user name of the board. For example, riscv.
- <Board_IP_Address>: The board IP address. For example, 192.168.92.133.

Example:

rsync ./test-gpio riscv@192.168.92.133:/home/riscv/test

3. Execute the following on VisionFive to run the demo code:

./test-gpio

The following is an example output:

Figure 4-2 Example Output

[root@fedora-	starfive test]#
[root@fedora-	starfive test]# ./test-gpio
*****	**************************************
****	*** StarF GPTO TEST DEMO **********
****	**** Version date: 2021/12 ***********
****	******
Gpio begin to	init .
Gpio init ok	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
Gpio off	
Gpio on	
<u>G</u> pio off	



- Gpio on: High voltage
- Gpio off: Low voltage