



StarFive  
赛昉科技

# JH7110 SDK Developer Guide for Display Controller

VisionFive 2

Version: 1.1

Date: 2023/8/11

Doc ID: JH7110-DGEN-014

# Legal Statements

Important legal notice before reading this documentation.

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# Preface

About this guide and technical support information.

## About this document

This document mainly provides the SDK developers with the programming basics and debugging know-how for the display module of the StarFive next generation SoC platform - JH7110.

## Audience

This document mainly serves the display module relevant driver developers. If you are developing other modules, place a request to your sales or support consultant for our complete documentation set on JH7110.






## Revision History

**Table 0-1 Revision History**

Version	Released	Revision
1.1	2023/8/11	Corrected the wrong command in <a href="#">Test Case Configuration (on page 20)</a> Step 1.
1.0		First official release.

## Notes and notices

The following notes and notices might appear in this guide:

-  **Tip:**  
Suggests how to apply the information in a topic or step.
-  **Note:**  
Explains a special case or expands on an important point.
-  **Important:**  
Points out critical information concerning a topic or step.
-  **CAUTION:**  
Indicates that an action or step can cause loss of data, security problems, or performance issues.
-  **Warning:**  
Indicates that an action or step can result in physical harm or cause damage to hardware.

# 1. Introduction

The display subsystem, named as **dom\_vout\_top** in the JH7110 system, includes front-end video data capture, display controller and display interface, such as RGB IF, HDMI, and MIPI.

In the display subsystem, DC8200 display controller works as a third party high-performance optimized-area *Display Processor Unit (DPU)* IP that can be used for reading rendered images from the frame buffer to the display.

See [Block Diagram \(on page 7\)](#) for more information.

## 1.1. Function Introduction

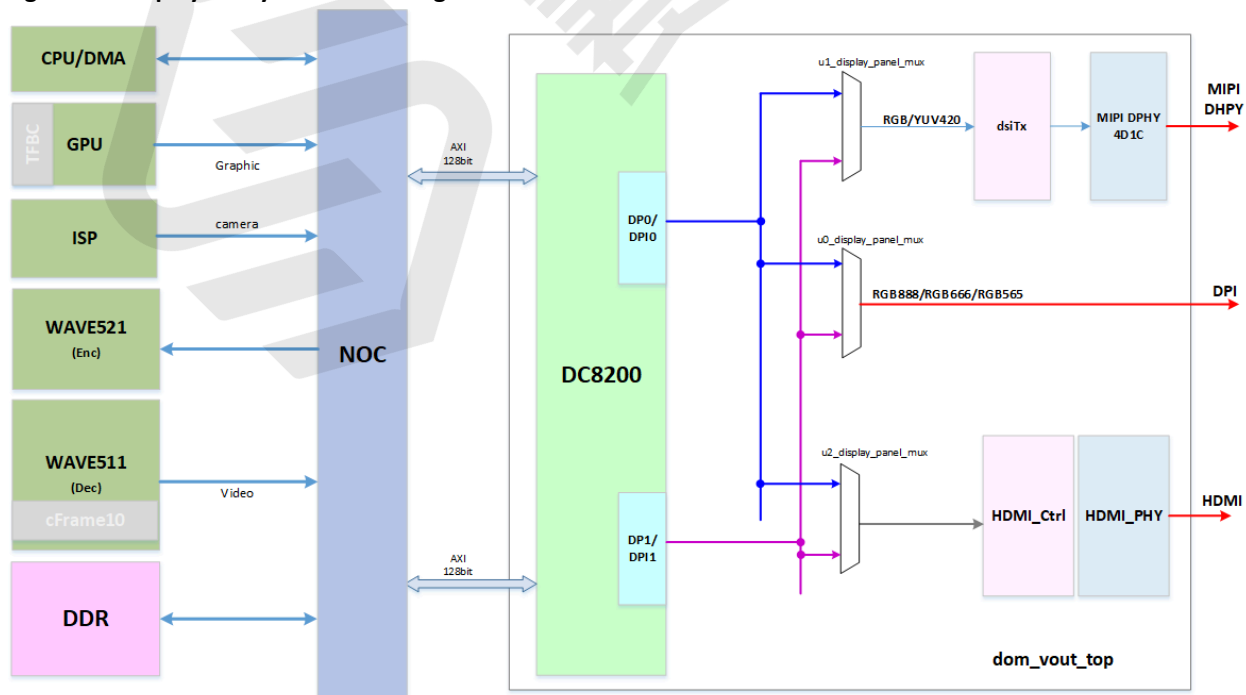
The display controller supports the following features:

- Support 2 display output panels
- Support 1 video/graphic layer per output panel
- Support 2 overlay layers per output panel
- Support 6 video/graphic and overlay layers
- Support 2 cursor layers
- Programmable cursor sizes: 32 × 32, 64 × 64
- Dynamic layer allocation support for video/graphic and overlay layers
- Support 2-screen display
- Support output interfaces: DP (RGB, YUV), DPI (RGB)

## 1.2. Block Diagram

The block diagram of the display subsystem is displayed in following diagram.

Figure 1-1 Display Subsystem Block Diagram



## Data Mapping

The DSI transmitter's pixel data could be from panel 0 or panel 1 interface of DC8200, and could be selected from DP or DPI interface. The RGB PAD and HDMI have similar mechanism.

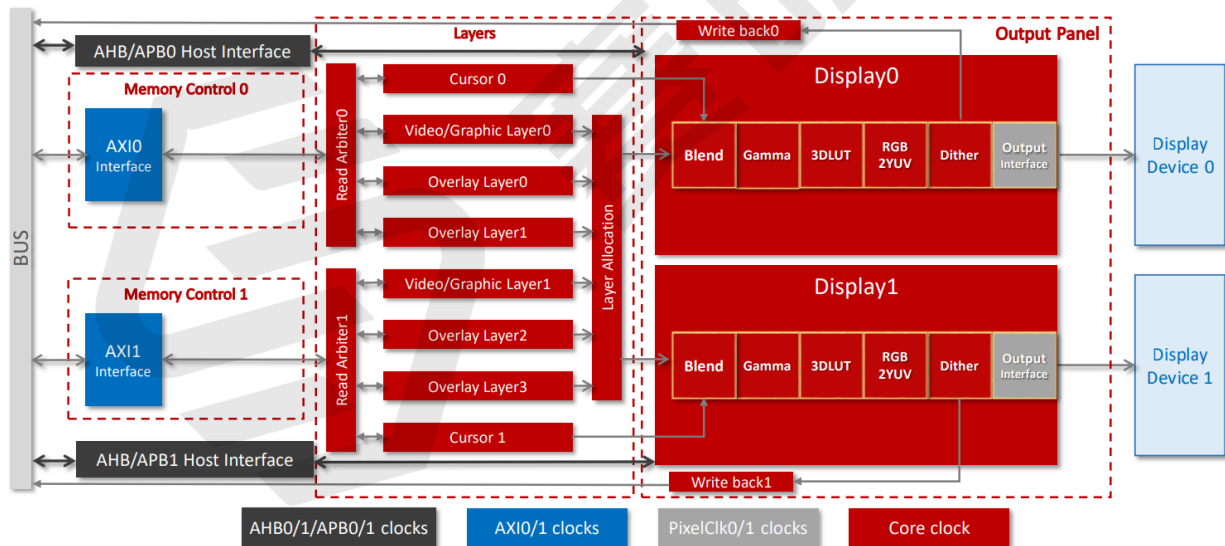
**Table 1-1 Display Subsystem Data Mapping**

Destination	Supported Data Mapping	Comment
DPI to PAD	<ul style="list-style-type: none"> <li>DP0/DP1 or DPI0/1 is used, default DPI is used.</li> <li>RGB24, RGB666 (CFG1), RGB565 (CFG1) when DPI is used.</li> </ul>	For flexibility
DSI Tx Data from DC8200	<ul style="list-style-type: none"> <li>Both DPI and DP are supported.</li> <li>YUV420 8-bit only (CFG3).</li> <li>YUV422 8-bit only (CFG1).</li> </ul>	Default DPI
HDMI Data from DC8200	<ul style="list-style-type: none"> <li>Both DP0 and DP1 are used for RGB and YUV.</li> <li>YUV444 and YUV422 8-bit/10-bit (CFG1).</li> <li>YUV420 8-bit/10-bit (CFG3).</li> </ul>	DP by default, and DPI for back-up

## 1.3. DC8200 Display Controller

The following image shows the block diagram of the DC8200 display controller.

**Figure 1-2 DC8200 Display Controller Block Diagram**



The following components are included.

- **Host Interface:** Allows communication with the system and the DC controller. The host interfaces include the AXI, AHB, and APB. In this block, data crosses clock domain boundaries.
- **Memory Control:** Contains the AXI interface to manage the access between the system memory and layers of the DC8200.
- **Write Back:** For debug use only.
- **Layers:** Include video/graphic, overlay, and cursor layers.



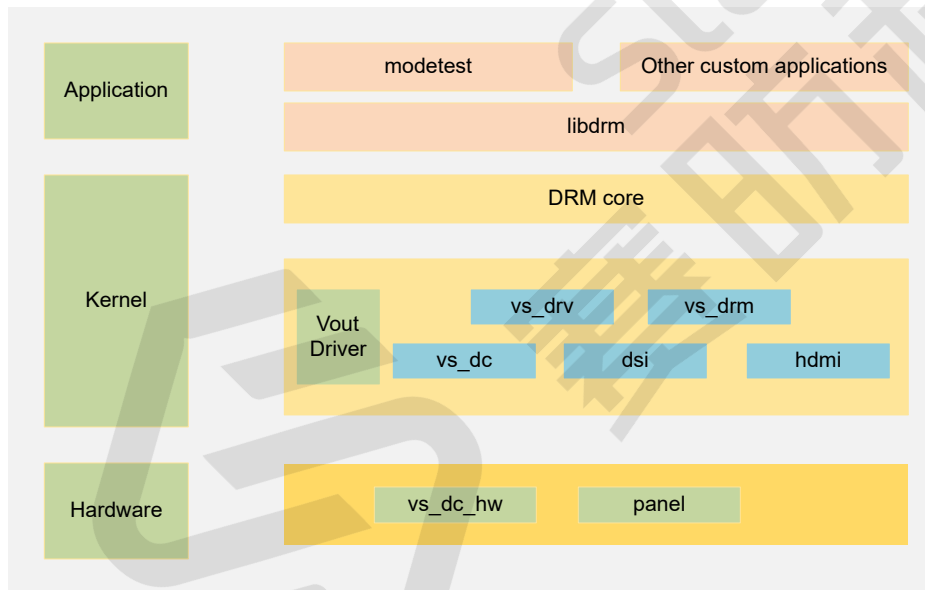
- Video/graphic layers support both video and graphic configurations. Video/graphic and overlay layers support dynamic layer allocation and de-gamma.
- Overlay 1 and overlay 3 do not support scaling, rotation, and line buffers.
- Cursor layers provide hardware cursor functionality.
- **Dither**: Provides a *Lookup Table (LUT)*.
- **Gamma**: Performs gamma correction.
- **Output Panels**: Support two output panels, as shown by Display0 and Display1.
- **Output Interfaces**: Support parallel pixel output with 30-bit Data, Horizontal Sync, Vertical Sync, and Data Enable. Support easy adaptation to external serialization logic, for example, HDMI.
- **Pixel Pipelines**: Reside in the layers and output panels. Two display pipelines support linear and tiled frame buffers for RGB and YUV inputs. Optional enhancements include multiple overlay layers, composition and blending, up/down scaling with multi-tap filtering, and color space conversions.

If you need more information, you may contact StarFive technical support and request documentation from the third-party IP.

## 1.4. Video Output Driver Framework

The following figure shows the framework of the video output driver and the display controller.

**Figure 1-3 Driver Framework**



The video output driver framework has the following 3 layers.

- **Application** layer consists of application code and test code and communicate with kernel layer through **libdrm**.
- **Kernel** layer consists of **DRM core** and **Vout driver**. **DRM core** receives commands from **libdrm** and transfer to **Vout driver**.
- **Hardware** layer is connected with **Vout driver**, and it operates the hardware directly.

## 1.5. Device Tree Overview

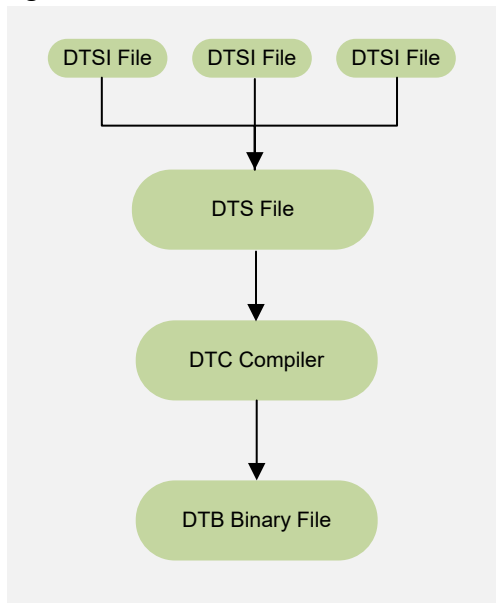
Since Linux 3.x, device tree is introduced as a data structure and language to describe hardware configuration. It is a system-readable description of hardware settings so that the operating system doesn't have to hard code details of the machine.

A device tree is primarily represented in the following forms.

- *Device Tree Compiler (DTC)*: The tool used to compile device tree into system-readable binaries.
- *Device Tree Source (DTS)*: The human-readable device tree description file. You can locate the target parameters and modify hardware configuration in this file.
- *Device Tree Source Information (DTSI)*: The human-readable header file which you can include in device tree description. You can locate the target parameters and modify hardware configuration in this file.
- *Device Tree Blob (DTB)*: The system-readable device tree binary blob files which is burned in system for execution.

The following diagram shows the relationship (workflow) of the above forms.

**Figure 1-4 Device Tree Workflow**



## 1.6. Source Code Structure

Locate the JH7110 *Software Development Kit (SDK)* with the following information.

- **Repository:** <https://github.com/starfive-tech/VisionFive2>
- **Branch:** JH7110\_VisionFive2\_devel
- **Tag:** Select the newest tag. For example, VF2\_v2.11.5 is newer than VF2\_v2.10.10.

The following code block shows the source code structure of the display controller.

```

linux-5.15.0
├-- drivers
├-- | --gpu
├-- | -- | -- drm
├-- | -- | -- | -- verisilicon
├-- | -- | -- | -- | -- vs_dc.c
├-- | -- | -- | -- | -- | -- vs_dc.h
├-- | -- | -- | -- | -- | -- vs_dc_hw.c
├-- | -- | -- | -- | -- | -- | -- vs_dc_hw.h
├-- | -- | -- | -- | -- | -- | -- vs_drv.c
├-- | -- | -- | -- | -- | -- | -- | -- vs_drv.h
├-- | -- | -- | -- | -- | -- | -- | -- vs_crtc.c
├-- | -- | -- | -- | -- | -- | -- | -- | -- vs_crtc.h
├-- | -- | -- | -- | -- | -- | -- | -- | -- vs_plane.c
├-- | -- | -- | -- | -- | -- | -- | -- | -- | -- vs_plane.h
├-- | -- | -- | -- | -- | -- | -- | -- | -- | -- vs_simple_enc.c
├-- | -- | -- | -- | -- | -- | -- | -- | -- | -- | -- vs_simple_enc.h
├-- | -- | -- | -- | -- | -- | -- | -- | -- | -- | -- vs_gem.c

```

```
| -- | -- | -- | -- | -- vs_gem.h  
| -- | -- | -- | -- | -- vs_virtual.c  
| -- | -- | -- | -- | -- vs_virtual.h  
| -- | -- | -- | -- | -- vs_dc_dec.c  
| -- | -- | -- | -- | -- vs_dc_dec.h
```



## 2. Configuration

### 2.1. Device Tree Configuration

#### Overview

A DTS/DTSI file is used to store all the device tree configuration.

The device tree of JH7110 is stored in the following path:

```
linux-5.10/arch/riscv/boot/dts/starfive/
```

The following code block shows the DTS file structure for JH7110.

```
linux-5.15.0
|-- arch
|   |-- riscv
|       |-- boot
|           |-- dts
|               |-- starfive
|                   |-- jh7110-common.dtsi
|                   |-- jh7110.dtsi
```

#### Display Subsystem

In the file `jh7110.dtsi`, you can find the device tree configuration of the display subsystem as the following code block:

```
display: display-subsystem {
    compatible = "starfive,jh7110-display","verisilicon,display-subsystem";
    ports = <&dc_out_dpi0>;
    status = "disabled";
dssctrl: dssctrl@295B0000 {
    compatible = "starfive,jh7110-dssctrl","verisilicon,dss-ctrl", "syscon";
    reg = <0 0X295B0000 0 0x90>;
};
```

The following list provides explanations for the parameters included in the above code block.

- **compatible:** Compatibility information, used to associate the display controller and its target device.
- **ports:** The port(s) used by the display controller.
- **status:** The work status of the display controller module. To enable the module, set this bit as "okay" or to disable the module, set this bit as "disabled".
- **reg:** Register base address "0x295B0000" and range "0x90".

#### DC8200

In the file `jh7110.dtsi`, you can find the device tree configuration of DC8200 (host) as the following code block:

```
dc8200: dc8200@29400000 {
    compatible = "verisilicon,dc8200";
    verisilicon,dss-syscon = <&dssctrl>;
    reg = <0x0 0x29400000 0x0 0x100>,
        <0x0 0x29400800 0x0 0x2000>,
        <0x0 0x17030000 0x0 0x1000>;
    interrupts = <95>;
    status = "disabled";
    clocks = <&clkgen JH7110_NOC_BUS_CLK_CPU_AXI>,
        <&clkgen JH7110_NOC_BUS_CLK_AXICFG0_AXI>,
        <&clkgen JH7110_NOC_BUS_CLK_GPU_AXI>,
        <&clkgen JH7110_NOC_BUS_CLK_VDEC_AXI>,
        <&clkgen JH7110_NOC_BUS_CLK_VENC_AXI>,
        <&clkgen JH7110_NOC_BUS_CLK_DISP_AXI>,
```

```

<&clkgen JH7110_NOC_BUS_CLK_ISP_AXI>,
<&clkgen JH7110_NOC_BUS_CLK_STG_AXI>,
<&clkgen JH7110_VOUT_SRC>,
<&clkgen JH7110_VOUT_TOP_CLK_VOUT_AXI>,
<&clkgen JH7110_AHB1>,
<&clkgen JH7110_VOUT_TOP_CLK_VOUT_AHB>,
<&clkgen JH7110_VOUT_TOP_CLK_HDMITX0_MCLK>,
<&clkgen JH7110_I2STX_4CH0_BCLK_MST>,
<&clkvout JH7110_U0_DC8200_CLK_PIX0>,
<&clkvout JH7110_U0_DC8200_CLK_PIX1>,
<&clkvout JH7110_U0_DC8200_CLK_AXI>,
<&clkvout JH7110_U0_DC8200_CLK_CORE>,
<&clkvout JH7110_U0_DC8200_CLK_AHB>,
<&clkgen JH7110_VOUT_TOP_CLK_VOUT_AXI>,
<&clkvout JH7110_DOM_VOUT_TOP_LCD_CLK>,
<&hdmitx0_pixelclk>,
<&clkvout JH7110_DC8200_PIX0>,
<&clkvout JH7110_U0_DC8200_CLK_PIX0_OUT>,
<&clkvout JH7110_U0_DC8200_CLK_PIX1_OUT>;

clock-names = "noc_cpu", "noc_cfg0", "noc_gpu", "noc_vdec", "noc_venc",
              "noc_disp", "noc_isp", "noc_stg", "vout_src",
              "top_vout_axi", "ahb1", "top_vout_ahb",
              "top_vout_hdmiTX0", "i2stx", "pix_clk", "vout_pix1",
              "axi_clk", "core_clk", "vout_ahb",
              "vout_top_axi", "vout_top_lcd", "hdmitx0_pixelclk", "dc8200_pix0",
              "dc8200_pix0_out", "dc8200_pix1_out";

resets = <&rstgen RSTN_U0_DOM_VOUT_TOP_SRC>,
        <&rstgen RSTN_U0_DC8200_AXI>,
        <&rstgen RSTN_U0_DC8200_AHB>,
        <&rstgen RSTN_U0_DC8200_CORE>,
        <&rstgen RSTN_U0_NOC_BUS_CPU_AXI_N>,
        <&rstgen RSTN_U0_NOC_BUS_AXICFG0_AXI_N>,
        <&rstgen RSTN_U0_NOC_BUS_APB_BUS_N>,
        <&rstgen RSTN_U0_NOC_BUS_DISP_AXI_N>,
        <&rstgen RSTN_U0_NOC_BUS_STG_AXI_N>;

reset-names = "rst_vout_src", "rst_axi", "rst_ahb", "rst_core",
              "rst_noc_cpu", "rst_noc_axicfg0", "rst_noc_apb",
              "rst_noc_disp", "rst_noc_stg";

power-domains = <&pwrc JH7110_PD_VOUT>;
};

```

The following list provides explanations for the parameters included in the above code block.

- **compatible:** Compatibility information, used to associate the display controller and its target device.
- **dss-syscon:** The SYSCON register(s) of the display panel.
- **reg:** Register base address "0x29400000" and range "0x100".
- **interrupts:** Hardware interrupt ID.
- **status:** The work status of the display controller module. To enable the module, set this bit as "okay" or to disable the module, set this bit as "disabled".
- **clocks:** The clocks used by the display controller module.
- **clock-names:** The names of the above clocks.
- **resets:** The reset signals used by the display controller module.
- **reset-names:** The names of the above reset signals.
- **power-domains:** The power supply domain of the display controller module.

In the file `jh7110-common.dtsi`, you can find the device tree configuration of DC8200 (endpoint) as the following code block:

```

&dc8200 {
    status = "okay";

    dc_out: port {
        #address-cells = <1>;
        #size-cells = <0>;
    };
};

```

## | 2 - Configuration

```
dc_out_dpi0: endpoint@0 {
    reg = <0>;
    remote-endpoint = <&hdmi_input0>;
};
dc_out_dpi1: endpoint@1 {
    reg = <1>;
    remote-endpoint = <&hdmi_in_lcdc>;
};

dc_out_dpi2: endpoint@2 {
    reg = <2>;
    remote-endpoint = <&mipi_in>;
};
};
};
```

The following list provides explanations for the parameters included in the above code block.

- **reg**: The register ID of the endpoint device.
- **remote-endpoint**: The endpoint device type of the display controller output.

## 2.2. Kernel Menu Configuration

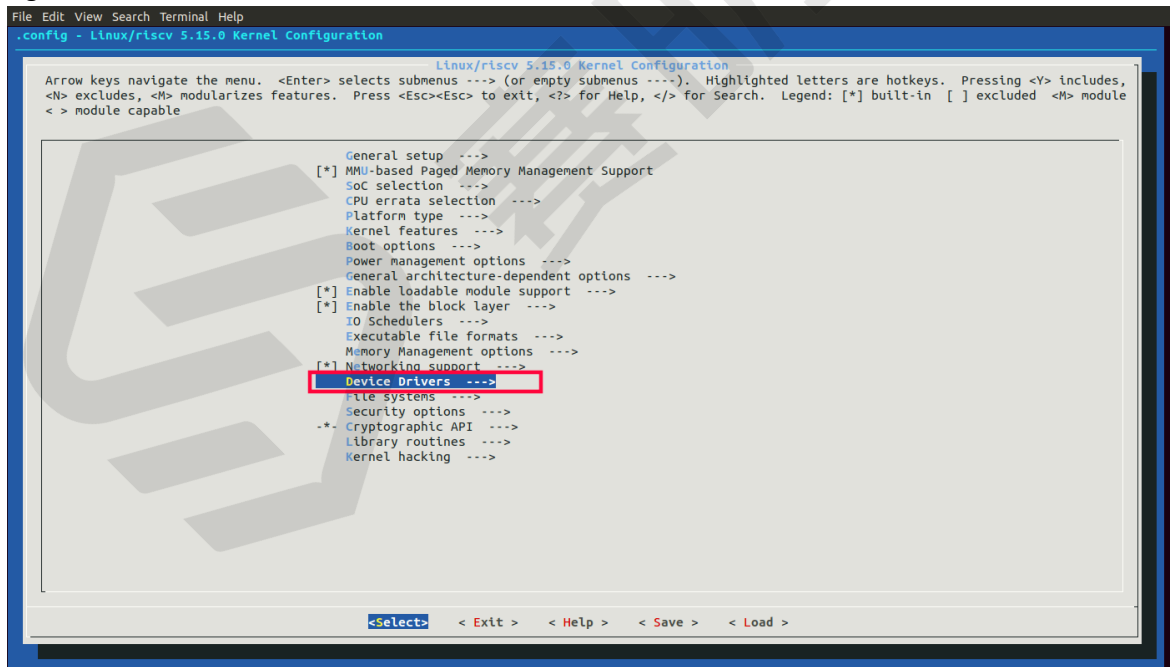
Follow the steps below to enable the kernel configuration for display controller.

1. Under the root directory of `freelight-u-sdk`, type the following command to enter the kernel menu configuration GUI.

```
make linux-menuconfig
```

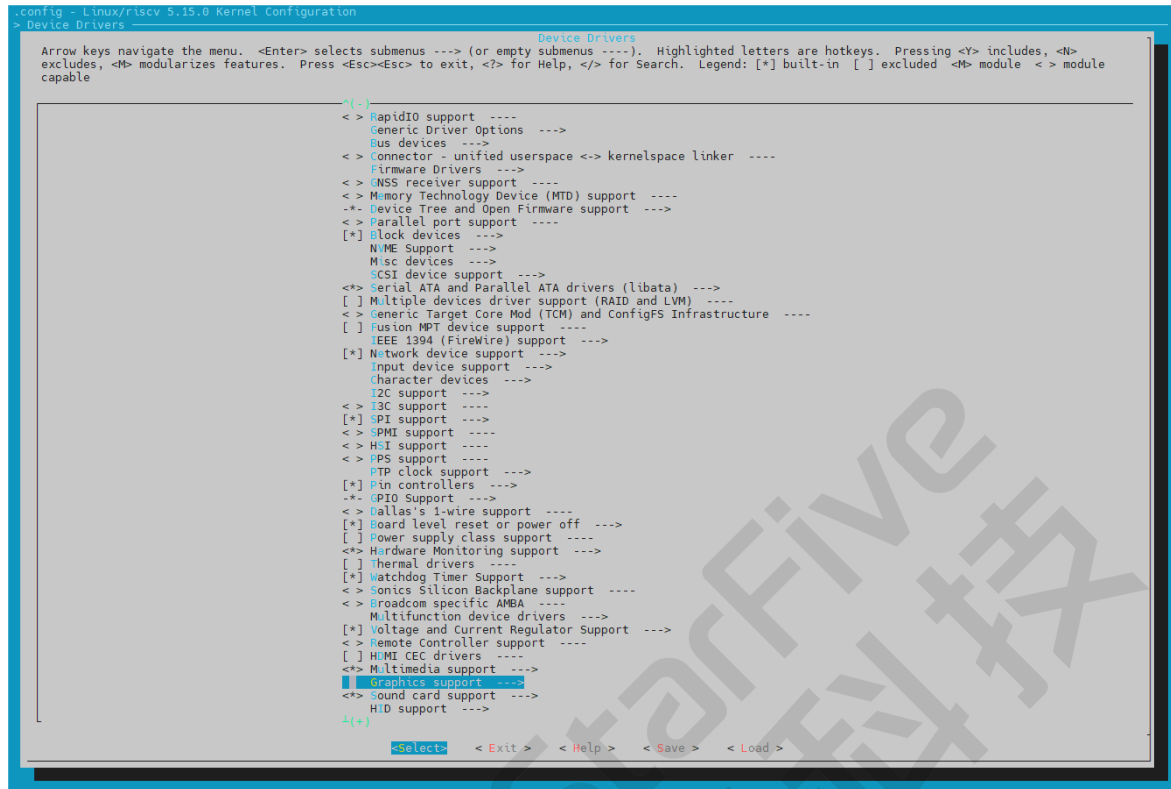
2. Enter the **Device Drivers** menu.

**Figure 2-1 Device Drivers**



3. Enter the **Graphics support** menu.

Figure 2-2 Graphics Support



4. Continue your settings per the sections below depending on your target output devices.

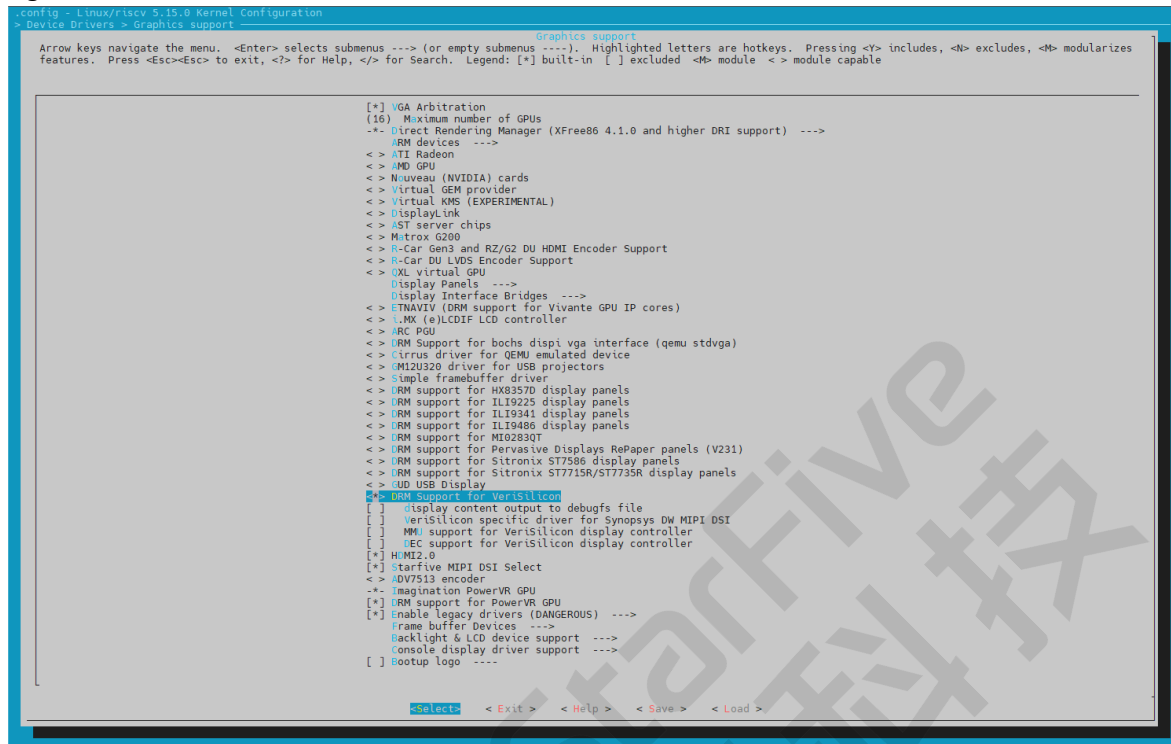
- [For HDMI output \(on page 15\)](#)
- [For MIPI output \(on page 16\)](#)
- [For RGB2HDMI output \(on page 17\)](#)

### For HDMI Output

Continue your settings with the following steps to enable the kernel configuration for HDMI output.

1. In the **Graphics support** menu, select the **HDMI2.0** option.

**Figure 2-3 HDMI2.0**



2. Save your change before you exit the kernel configuration dialog.

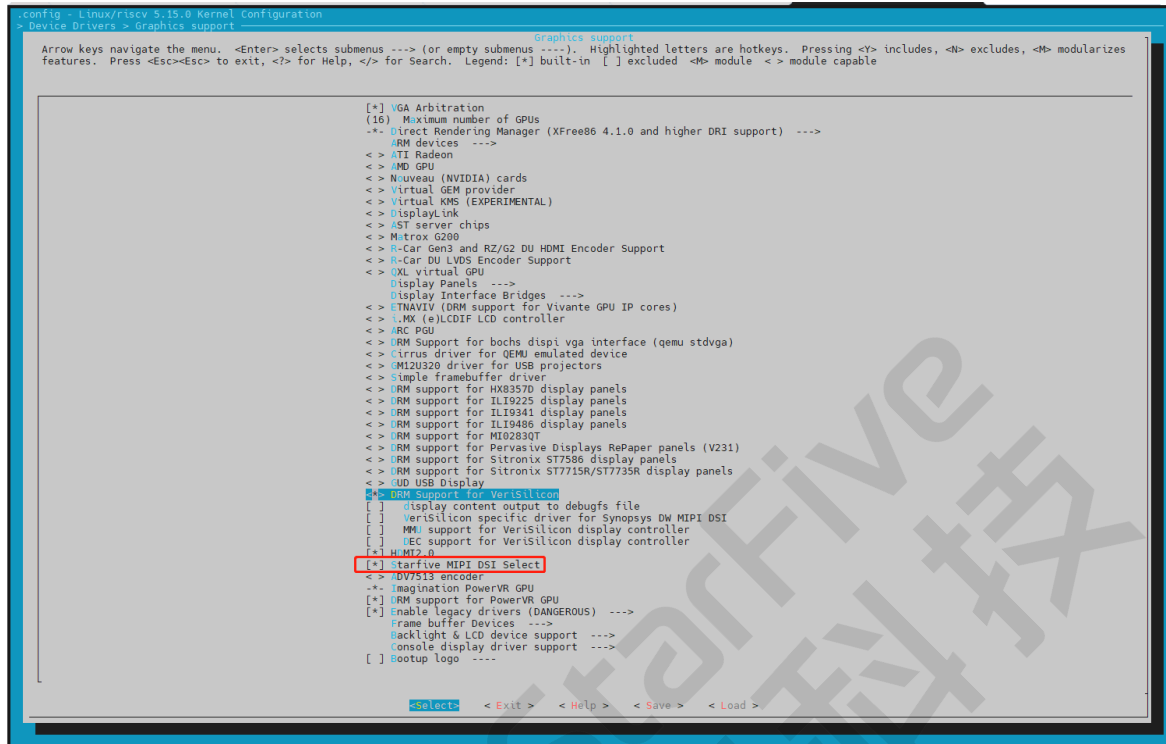
### For MIPI Output

Continue your settings with the following steps to enable the kernel configuration for MIPI output.



1. In the **Graphics support** menu, select the **Starfive MIPI DSI Select** option.

**Figure 2-4 MIPI DSI Select**



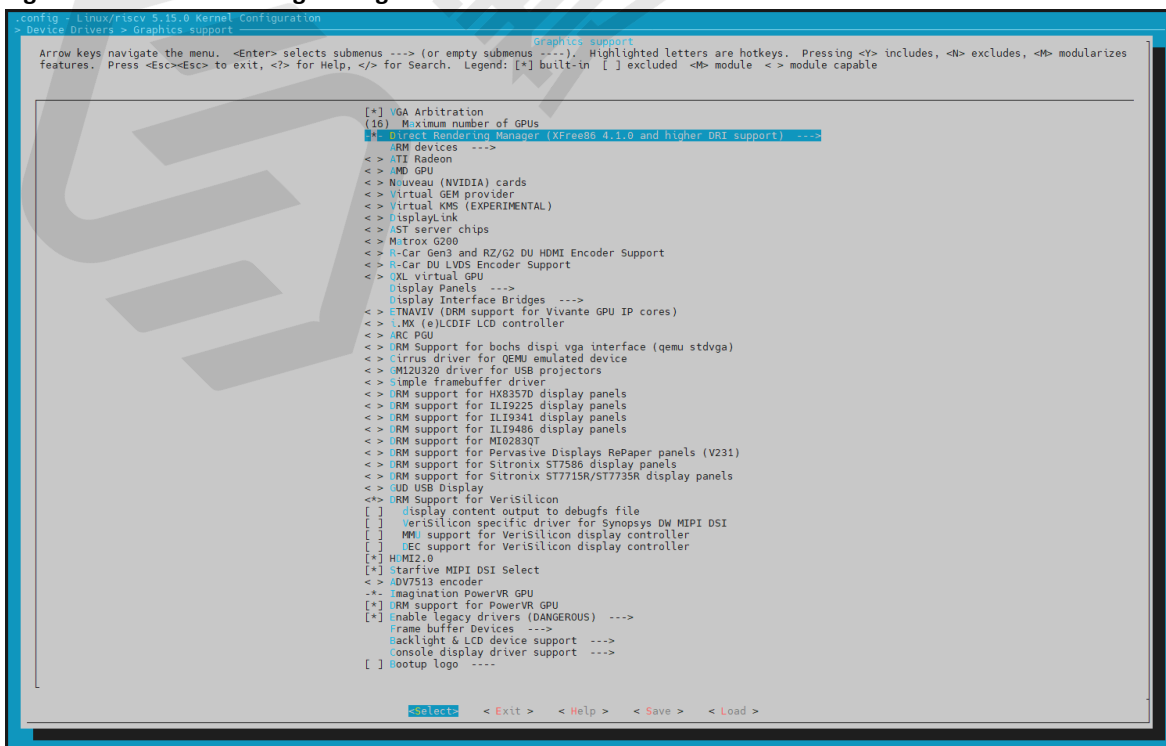
2. Save your change before you exit the kernel configuration dialog.

## For RGB2HDMI Output

Continue your settings with the following steps to enable the kernel configuration for RGB2HDMI output.

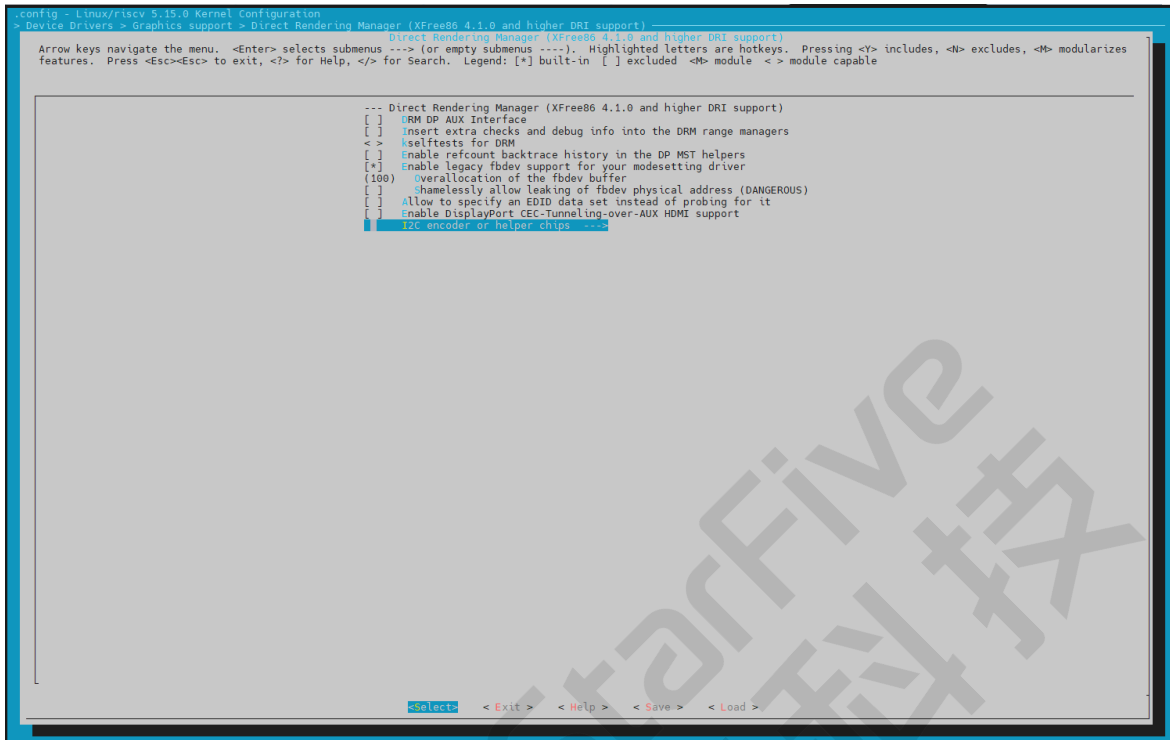
1. In the **Graphics support** menu, select and enter the **Direct Rendering Manager** menu.

**Figure 2-5 Direct Rendering Manager**



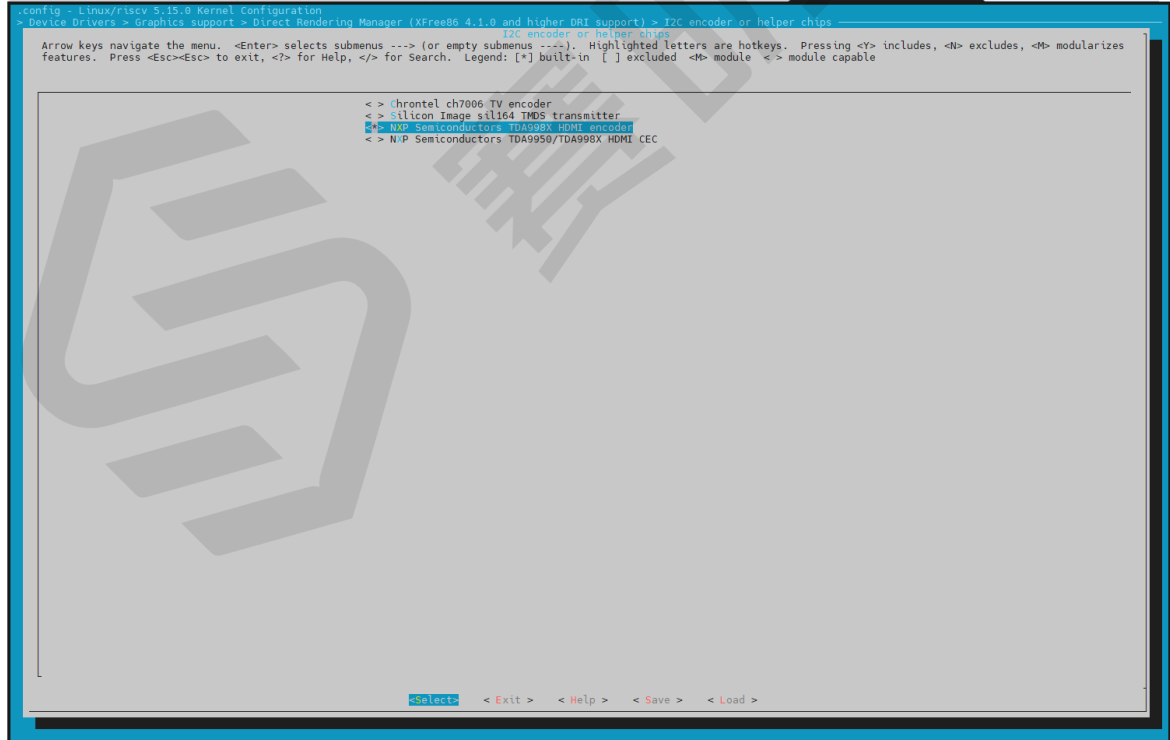
2. In the **Direct Rendering Manager** menu, select and enter the **I2C encoder or helper chips** menu.

**Figure 2-6 I2C Encoder or Other Helper**



3. In the **I2C encoder or helper chips** menu, select the **NXP Semiconductors TDA998X HDMI encoder** option.

**Figure 2-7 NXP Semiconductors TDA998X**



4. Save your change before you exit the kernel configuration dialog.

## 2.3. Driver Configuration

The following code block shows the driver configuration.

```
CONFIG_DRM_VERISILICON=y
```



## 3. Debug Method

### 3.1. Test Case Configuration

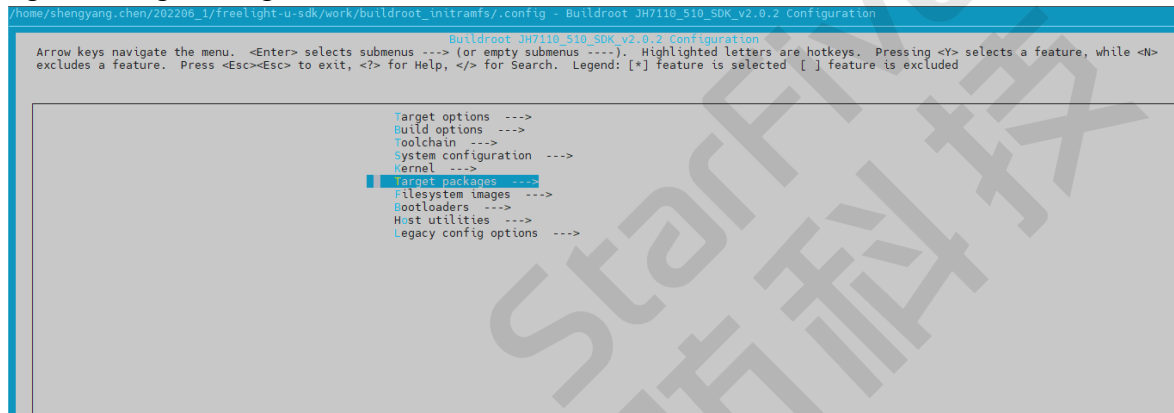
Follow the steps below to enable the kernel configuration.

1. Under the root directory of `freelight-u-sdk`, type the following command to enter the kernel menu configuration GUI.

```
make buildroot_initramfs-menuconfig
```

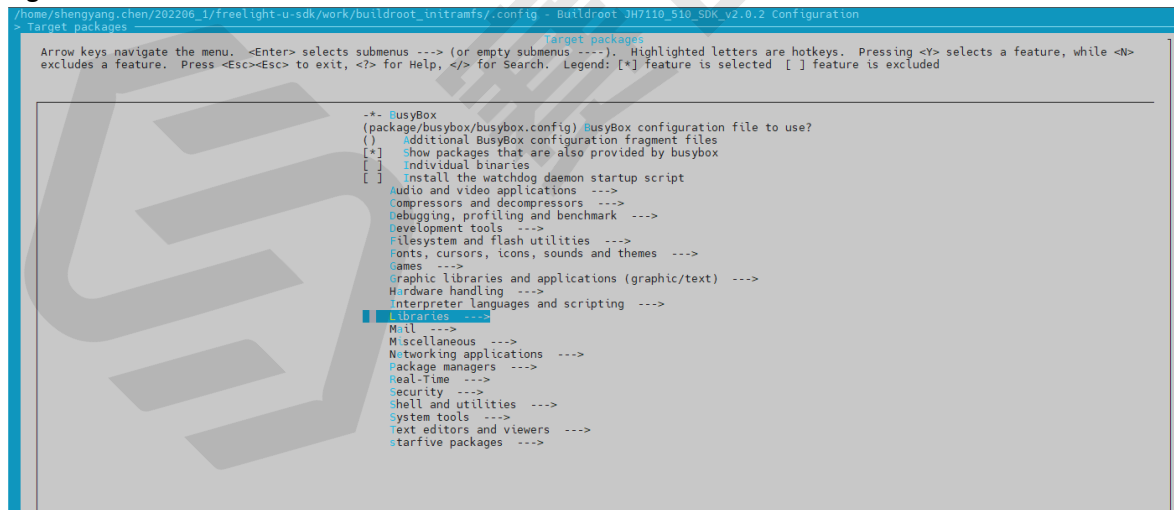
2. Enter the **Target packages** menu.

**Figure 3-1 Target Packages**



3. Enter the **Libraries** menu.

**Figure 3-2 Libraries**



4. Enter the **Graphics** menu.

Figure 3-3 Graphics

```

/home/shengyang.chen/202206_1/freelight-u-sdk/work/buildroot_initramfs/.config - Buildroot JH7110_510_SDK_v2.0.2 Configuration
> Target packages > Libraries
Libraries
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenu --->). Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N>
excludes a feature. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is selected [ ] feature is excluded

Audio/Sound --->
Compression and decompression --->
Crypto --->
Database --->
Filesystem --->
Graphics --->
Hardware handling --->
Javascript --->
JSON/XML --->
Logging --->
Multimedia --->
Networking --->
Other --->
Security --->
Text and terminal handling --->

```

5. Enter the `libdrm` menu.

Figure 3-4 libdrm

```

/home/shengyang.chen/202206_1/freelight-u-sdk/work/buildroot_initramfs/.config - Buildroot JH7110_510_SDK_v2.0.2 Configuration
> Target packages > Libraries > Graphics
Graphics
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenu --->). Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N>
excludes a feature. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is selected [ ] feature is excluded

[ ] assimp
*** at-spi2-atk depends on X.org ***
*** at-spi2-core depends on X.org ***
[ ] atk
[ ] atkmm
[ ] bullet
+* cairo
[ ] cairo
*** chipmunk needs an OpenGL backend ***
[ ] exempi
[ ] exiv2
-* fontconfig
-* freetype
[ ] gd
[ ] gdk-pixbuf
[ ] giflib
*** granite needs libgtk3 and a toolchain w/ wchar, threads ***
[ ] graphite2
*** gtkmm3 needs libgtk3 and a toolchain w/ C++, wchar, threads, gcc >= 4.9 ***
-* harfbuzz
[ ] ijs
[ ] mlb2
*** irrlicht needs X11 and an OpenGL provider ***
[ ] Jasper
[ ] big2dec
-* jpeg support
  jpeg variant (jpeg) --->
[ ] m2++
[ ] ccs2
[ ] lensfun
[ ] leptonic
[ ] libart
[ ] libdmtx
+* libdrm --->
[ ] libepoxy
[ ] libexif
*** libfm needs X.org and a toolchain w/ wchar, threads, C++, gcc >= 4.8 ***
[ ] libfm-extra
*** libfreeglut depends on X.org and needs an OpenGL backend ***
[ ] libfreeimage
[ ] libgeotiff
*** libglw depends on X.org and needs an OpenGL backend ***
*** libglwf depends on X.org and needs an OpenGL backend ***
*** libglu needs an OpenGL backend ***
[ ] libgta
[ ] libgtk3
[ ] libmediaart
[ ] libmng
-* libpng
[ ] libqrencode

```

6. Select the **Install test programs** option, or you may select ALL options under this menu.

Figure 3-5 Install Test Programs

```

/home/shengyang.chen/202206_1/freelight-u-sdk/work/buildroot_initramfs/.config - Buildroot JH7110_510_SDK_v2.0.2 Configuration
> Target packages > Libraries > Graphics > libdrm
libdrm
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenu --->). Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N>
excludes a feature. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is selected [ ] feature is excluded

--- libdrm
[ ] radeon
[ ] amdgpu
[ ] nouveau
[ ] tnaviv (experimental)
[*] Install test programs

```

**Result:** After you have completed all the above configuration, you can use the `modetest` tool in kernel for testing.

7. Save your change before you exit the kernel configuration dialog.

## 3.2. Before Debug

Before debugging the display controller, make sure you see the following screen in the start-up logs.

**Figure 3-6 Start-up Logs**

```

6.827275] mmc_host mmc0: Bus speed (slot 0) = 198000000Hz (slot req 200000Hz, actual 200000Hz div = 495)
6.827542] DC_CURSOR_FOREGROUND + 0 = 0
6.840870] DC_CURSOR_FOREGROUND + 0 = aaaaaa
6.845226] DC_CURSOR_FOREGROUND + 1 = 0
6.849161] DC_CURSOR_FOREGROUND + 1 = aaaaaa
6.853766] starfive soc:display-subsystem: bound 29400000.dc8200 (ops 0xffffffff80e73c88)
6.862977] platform regulatory.0: Direct firmware load for regulatory.db failed with error -2
6.871620] cfg80211: failed to load regulatory.db
6.871962] innohdmi-starfive 29590000.hdmi: [drm:inno_hdmi_bind] registered Inno HDMI I2C bus driver success
6.886475] starfive soc:display-subsystem: bound 29590000.hdmi (ops 0xffffffff80e74af0)
6.894579] vs-simple-encoder soc:rgb-output: encoder_bind begin
6.900619] vs-simple-encoder soc:rgb-output: encoder_bind end
6.906456] starfive soc:display-subsystem: bound soc:rgb-output (ops 0xffffffff80e74738)
6.914641] vs-simple-encoder soc:dsi-output: encoder_bind begin
6.920739] cdns-dsi 295d0000.mipi: ==>cdns_dsi_bridge_attach begin
6.927091] cdns-dsi 295d0000.mipi: ==>cdns_dsi_bridge_attach end
6.933294] vs-simple-encoder soc:dsi-output: encoder_bind end
6.939140] starfive soc:display-subsystem: bound soc:dsi-output (ops 0xffffffff80e74738)
6.947967] [drm] initialized starfive 1.0.0 20191101 for soc:display-subsystem on minor 1
7.287268] mmc_host mmc0: Bus speed (slot 0) = 198000000Hz (slot req 100000Hz, actual 100000Hz div = 990)
8.977276] ALSA device list:
8.980246]   No soundcards found.
8.985685] Freeing unused kernel image (initmem) memory: 2168k
8.991729] Run /init as init process
8.995392]   with arguments:
8.998368]   /init
9.000640]   with environment:
9.003781]   HOME=/
9.006139]   TERM=linux
Starting syslogd: OK
Starting klogd: OK
Running sycstl: OK

```

**Table 3-1 Start-up Logs**

Legend	Description
①	HDMI work status
②	RGB2HDMI work status
③	MIPI work status
④	Display controller work status

The log lines showing display controller and the HDMI are required before the debug.



**Note:**

Verify the connection status if you cannot find the above log records.

## 3.3. Debug Display

Follow the steps below to debug the display functions for your JH7110.

1. Follow the steps in [Test Case Configuration \(on page 20\)](#) to configure the test environment.



**Note:**

Make sure you have configured **libdrm** and **modetest** before compiling and burning an image.

2. After you have completed the kernel start-up, use the following command to verify the display functions and connection status.

```
modetest -M starfive
```

The following legends and tables display an example output and descriptions.

◦ Debug output 1:

**Figure 3-7 Debug Display 1**

```
# modetest -M starfive
Encoders:
id      crtc   type      possible crtcs  possible clones
115     0        TMDS     0x00000001     0x00000001
117     0        DSI      0x00000002     0x00000002

Connectors:
id      encoder  status      name          size (mm)    modes    encoders
116     0        connected   HDMI-A-1     0x0          10       115

modes:
index name refresh (Hz) hdisp hss hse htot vdisp vss vse vtot
#0 1920x1080 60.00 1920 2008 2052 2200 1080 1084 1089 1125 148500 flags: phsync, pvsync; type: driver
#1 1920x1080 59.94 1920 2008 2052 2200 1080 1084 1089 1125 148352 flags: phsync, pvsync; type: driver
#2 1920x1080 50.00 1920 2448 2492 2640 1080 1084 1089 1125 148500 flags: phsync, pvsync; type: driver
#3 1280x720 60.00 1280 1390 1430 1650 720 725 730 750 74250 flags: phsync, pvsync; type: driver
#4 1280x720 59.94 1280 1390 1430 1650 720 725 730 750 74176 flags: phsync, pvsync; type: driver
#5 1280x720 50.00 1280 1720 1760 1980 720 725 730 750 74250 flags: phsync, pvsync; type: driver
#6 1280x720 48.00 1280 2240 2280 2500 720 725 730 750 90000 flags: phsync, pvsync; type: driver
#7 1280x720 47.95 1280 2240 2280 2500 720 725 730 750 89910 flags: phsync, pvsync; type: driver
#8 640x480 60.00 640 656 752 800 480 490 492 525 25200 flags: nhsync, nvsync; type: driver
#9 640x480 59.94 640 656 752 800 480 490 492 525 25175 flags: nhsync, nvsync; type: driver

props:
1 EDID:
  flags: immutable blob
  blobs:
  value:
    00ffffffffffff004a8b201980102019
    001e010380000078ecee91a3544c9926
    0f5054230800d1c0b300950081006140
    4540814081c0023a801871382d40582c
    250058c31000001e000000fc00000a20
    202020202020202020202000000ff0000
    0a202020202020202020202000000fd
    00383f545413000a20202020202001a3
    020332f24f04051013141f6c6c6c276c
    6c6c4b4ce200d5e305c00023097f0783
    01000067030c001000383ca606050169
    694f023a801871382d40582c250058c3
    1000001e011d8018711c1620582c2500
    58c31000009e00000000000000000000
    00000000000000000000000000000000
    00000000000000000000000000007a

2 DPMS:
  flags: enum
  enums: On=0 Standby=1 Suspend=2 Off=3
  value: 0

5 link-status:
  flags: enum
  enums: Good=0 Bad=1
  value: 0

6 non-desktop:
  flags: immutable range
  values: 0 1
```

**Table 3-2 Debug Display 1**

Legend	Label	Description
①	<b>possible crtcs</b>	Available <i>Cathode Ray Tube Controller (CRTC)</i> devices
②	<b>status</b>	Whether the display connector is connected or not
③	<b>name</b>	The name (type) of the display connector
④	<b>encoders</b>	The connected encoders
⑤	<b>modes</b>	The supported display modes
⑥	<b>value</b>	The <i>Extended Display Identification Data (EDID)</i> of the screen

◦ Debug output 2:

**Figure 3-8 Debug Display 2**

```

CRTCs:
id ① fb      pos      size
31 0      (0,0)  (0x0)
#0 nan 0 0 0 0 0 0 0 0 0 0 flags: ; type:
props:
  24 VRR_ENABLED:
      flags: range
      values: 0 1
      value: 0
  28 GAMMA_LUT:
      flags: blob
      blobs:

      value:
  29 GAMMA_LUT_SIZE:
      flags: immutable range
      values: 0 4294967295
      value: 300
  32 BG_COLOR:
      flags: range
      values: 0 4294967295
      value: 0
  33 SYNC_ENABLED:
      flags: range
      values: 0 1
      value: 0
  34 DITHER_ENABLED:
      flags: range
      values: 0 1
      value: 0
id ② fb      pos      size
35 0      (0,0)  (0x0)
#0 nan 0 0 0 0 0 0 0 0 0 0 flags: ; type:
props:
  24 VRR_ENABLED:
      flags: range
      values: 0 1
      value: 0
  28 GAMMA_LUT:
      flags: blob
      blobs:

      value:
  29 GAMMA_LUT_SIZE:
      flags: immutable range
      values: 0 4294967295
      value: 300
  36 BG_COLOR:
      flags: range
      values: 0 4294967295
      value: 0
  37 SYNC_ENABLED:
      flags: range
      values: 0 1
      value: 0
  38 DITHER_ENABLED:
      flags: range
      values: 0 1
      value: 0

Planes:

```

**Table 3-3 Debug Display 2**

Legend	Label	Description
①	id	The CRTC 0x00000001 mentioned in row ① of table <a href="#">Table 3-2</a> : <a href="#">Debug Display 1 (on page 23)</a> , which means the CRTC is available for use.





### For MIPI Output

The following command shows an example for testing the MIPI output.

```
modetest -M starfive -D 0 -a -s 118@35:800x480 -P 74@35:800x480@RG16
```

The following list provides explanations for the parameters in the above example command.

- **118@35:800x480** - <Connector ID>@<CRTC ID>: <Resolution>
- **74@35:800x480@RG16** - <Plane ID>@<CRTC ID>: <Resolution>@<Format>

### For RGB2HDMI Output

The following command shows an example for testing the MIPI output.

```
modetest -M starfive -D 0 -a -s 118@35:1920x1080 -P 74@35:1920x1080@RG16 -Ftiles
```

The following list provides explanations for the parameters in the above example command.

- **118@35:1920x1080** - <Connector ID>@<CRTC ID>: <Resolution>
- **74@35:1920x1080@RG16** - <Plane ID>@<CRTC ID>: <Resolution>@<Format>

### For Both MIPI and RGB2HDMI Outputs

If your board is connected with both a MIPI and a RGB2HDMI output devices, the following commands show an example for testing on each of them.

- For MIPI:

```
modetest -M starfive -D 0 -a -s 120@35:800x480 -P 74@35:800x480@RG16
```

- **120@35:800x480** - <Connector ID>@<CRTC ID>: <Resolution>
- **74@35:800x480@RG16** - <Plane ID>@<CRTC ID>: <Resolution>@<Format>

- For RGB2HDMI:

```
modetest -M starfive -D 0 -a -s 118@35:1920x1080 -P 74@35:1920x1080@RG16 -Ftiles
```

- **118@35:1920x1080** - <Connector ID>@<CRTC ID>: <Resolution>
- **74@35:1920x1080@RG16** - <Plane ID>@<CRTC ID>: <Resolution>@<Format>

### Output Result

The following photo shows the output generated from the above example command.

Figure 3-10 Test Example



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